# Reservoir Computing Techniques Using Tensor Networks

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*Abstract*—Reservoir computing (RC), traditionally based on echo state networks and liquid state machines, shows great potential in modeling dynamic time-series data like weather and astronomical predictions. However, these frameworks are not suitable for quantum dynamics-based RC. Tensor networks (TNs) are well suited for modeling quantum dynamics because they can efficiently model quantum information and entanglement. In this work, we propose a novel randomized TN-based RC scheme, demonstrating its validity through various case studies. Our results show superior performance compared to traditional ESN models, laying the groundwork for further exploration of quantum reservoir computing.

*Index Terms*—Reservoir Computing (RC), Tensor Networks (TN), Quantum Dynamics.

### I. INTRODUCTION

### A. Background

Reservoir computing (RC) has established itself as a powerful approach for learning dynamic temporal data, primarily through frameworks like echo state networks (ESNs) and liquid state machines, where only the output weights are trained, and internal weights remain fixed [1]–[13]. Traditional RC, however, struggles with quantum dynamics due to limitations in representing high-dimensional quantum information and entanglement [14]–[17]. Tensor networks (TNs) provide a promising alternative for quantum RC by enabling the handling of complex quantum correlations and entanglement [18]–[30]. By introducing randomized effects into TNs, akin to the randomization in traditional RC, diverse quantum correlation patterns are generated, resulting in robust and generalizable quantum dynamic models [31]–[41].

# B. Our results

In this study, we explore the TNRC approach for both static data classification and time-series dynamic predictions, with the following key findings:

1) The proposed TNRC method is computationally efficient, avoiding the high computational costs typical of traditional TN training.

- Numerical calculations of IPC for time-series data show scaling behavior near the edge of chaos, resembling patterns observed in RC settings for digit classification.
- 3) Calculations indicate a universal normalized entanglement entropy predicting phase boundaries across various cases. Our research bridges the gap between traditional RC frameworks and quantum dynamics, utilizing randomized tensor networks to offer new insights into learnability and phase transitions within complex quantum systems.

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### II. METHODS

### A. Summary of Learning Architecture

The training dataset is denoted as  $D = \{(\vec{x}^{[n]}, \vec{y}^{[n]})\}_{n=1}^{m}$ where each input vector  $\vec{x}^{[n]} = (x_1^{[n]}, x_2^{[n]}, \dots, x_N^{[n]}) \in [0, 1]^N \subset \mathbb{R}^N$  and m represents the dataset size, while N is the input dimension. The output  $\vec{y} = (y_1, y_2, \dots, y_{|c|})$  is one-hot encoded for classification, determined as:  $y_i = \delta_{i,k}, k = \underset{j \in c}{\operatorname{argmax}} \sum_{l=0}^{L-1} W_{j,l} F_l(\vec{x})$  with  $F_l(\vec{x}) = \sigma(f^{(l)}(\vec{x}))$ , where  $\sigma(z) = \frac{1}{1+e^{-z}}$  is the logistic sigmoid, and W is the trainable weight matrix.

The model utilizes a hybrid tensor-neural network with tensor-based decision functions and feature maps. For image input, the scikit-learn hand-written digit dataset [42]-[43] (8x8 grayscale images) is serialized, resulting in N = 64 and MPS reservoir length N + 1 = 65. The class set for output is  $c = \{0, 1, \ldots, 9\}$ , and a quadratic loss is used for training, with W obtained via Moore-Penrose pseudoinverse.

The decision function  $f^{(l)}(\vec{x})$  is expressed as:

$$f^{(l)}(\vec{x}) = \sum_{i_1, i_2, \dots, i_N = 0}^{1} \Psi^{(l)}_{i_1, i_2, \dots, i_N} \phi_{i_1}(x_1) \phi_{i_2}(x_2) \cdots \phi_{i_N}(x_N)$$
(1)

where  $\Psi$  is approximated by a Matrix Product State (MPS) as:

$$\Psi_{i_{1},i_{2},...,i_{N}}^{(l)} = \sum_{\alpha_{1},\alpha_{2},...,\alpha_{N}=0}^{\chi-1} A_{i_{1},0,\alpha_{1}}^{(1)} A_{i_{2},\alpha_{1},\alpha_{2}}^{(2)} \dots A_{i_{\frac{N}{2}}}^{\left(\frac{N}{2}\right)}, \alpha_{\left(\frac{N}{2}-1\right)}^{\left(\frac{N}{2}\right)} \times A_{l,\alpha_{\left(\frac{N}{2}\right)}^{(out)}}^{(out)} A_{i_{\frac{N}{2}+1}}^{\left(\frac{N}{2}+1\right)}, \alpha_{\left(\frac{N}{2}+1\right)}^{\left(\frac{N}{2}+1\right)}, \alpha_{\frac{N}{2}+2}^{(N)} \dots A_{i_{N},\alpha_{N},0}^{(N)} \tag{2}$$

Here,  $\chi$  denotes the bond dimension, and A matrices are randomly initialized from a Gaussian ensemble. MPS length is N + 1, and basis functions for input encoding are  $\phi_0(x) = 1 - x$  and  $\phi_1(x) = x$ . The MPS representation reduces the parameter count to  $O(N\chi^2 L)$ , making it an efficient compression for high-rank tensors, as opposed to the full representation of  $2^N L$ . During training, the MPS remains fixed. Entanglement entropy S is calculated for the MPS in mixed canonical form, normalized as  $\tilde{S} = S/\log_2 \chi \in [0, 1]$ .  $\tilde{S} = 1$  implies maximal entanglement, and  $\tilde{S} = 0$  indicates no entanglement.



Fig. 1. The data flow from input to output of TNRC.

# *B. Reservoir Computing and Information Processing Capacity* (*IPC*)

In this approach using reservoir computing for sequential data learning, each 8×8 image is divided into four sections, each containing 16 pixels. This transforms the image into four time slices, with each slice providing a 16-dimensional input vector  $u_j(t)$  at time  $t \in \{1, 2, 3, 4\}$ . The iterative function is defined as follows:  $T_l(x_t, \zeta_t) = \sigma(f^{(l)}(\vec{x}_t) + \iota \sum_{j=1}^M W_{in,l,j}u_j(t))$ . The final output is determined by:  $y = \underset{i \in c}{\operatorname{argmax}} \sum_{l=1}^N W_{out,i,l}\sigma(f^{(l)}(\vec{x}_t) + \iota \sum_{j=1}^M W_{in,l,j}u_j(t))$  where M = 16, N = 64, and t = 4. Information Processing Capacity (IPC) is a measure based on memory capacity,

evaluating how effectively the reservoir can model time-series data [44]. A system in a stable or chaotic state has low IPC, while a system at the edge of chaos has high IPC. For IPC calculation, we used the code provided by [45]. The time series is calculated using the transition function  $T : \mathbb{R}^N \times \mathbb{R} \longrightarrow \mathbb{R}^N$ as follows:  $x_{t+1} = \vec{T}(\vec{x}_t, \zeta_t)$  for uniformly distributed random input signal  $\zeta_t \in [-1, 1]$ . The transition function for tensor network-based reservoir computing is given by:  $T_l(\vec{x}_t, \zeta_t) =$  $\sigma(f^{(l)}(\vec{x}_t) + \iota W_{in,l}\zeta_t)$  where the input weight vector  $W_{in}$ is randomly drawn from the interval [-1, 1], and a scaling constant  $\iota = 0.1$  is set. This flow is shown in Fig. 1.

### III. RESULTS AND DISCUSSIONS

## A. IPC and Dynamic Data

The IPC analysis for time-series data demonstrates the transition behavior as the system approaches the chaotic phase. Using N = 64 for IPC calculation, Fig 2(a) shows that IPC starts at a low value in the stable phase, rises to its theoretical maximum  $C_{tot} = N$  near the edge of chaos, and declines sharply as the system enters chaos. This phase transition highlights the system's stability and information-processing capacity. Fig. 2(b) provides a detailed phase diagram, showing that IPC reaches optimal values near the edge of chaos, reinforcing the framework's robustness across various datasets. Additionally, Fig. 2(c) illustrates the phase transition using handwritten digit data, confirming the adaptability of the IPC framework across different input dimensions and datasets.

## B. Entanglement Entropy of Randomized MPS Reservoirs

The entanglement entropy of the randomized MPS reservoir is examined to understand its relationship with model performance. As the standard deviation  $\sigma_A$  of the Gaussian ensemble increases, the entanglement entropy also increases. Fig. 3(a) shows IPC plotted against the entanglement entropy, with phase transition points occurring consistently at the same entropy level across bond dimensions. Additionally, Fig. 3(b) reveals that the normalized entanglement entropy and test accuracy is observed for RC learning, with optimal fitting seen within  $\tilde{S} \in [0.1, 0.5]$ . The results suggest that higher entanglement does not necessarily improve learning performance, aligning with known findings in quantum information theory [46]-[47].



Fig. 2. The IPC for 64-dimensional input-output time series and RC learning data. (a) The IPC phase diagram (b) The phase diagram for the test accuracy of RC learning.

### IV. CONCLUSION

This article introduces and demonstrates the TNRC method, validating its low-cost learning approach through a handwritten digit classification experiment. Empirical and theoretical analyses reveal learnability phase transitions in the random tensor reservoir, moving from underfitting to overfitting. The order-to-chaos criticality in reservoir computing (RC) is numerically evaluated using IPC and observed in time-sequence data experiments, with theoretical insights explaining these transitions. The entanglement entropy appears to play a role in these phase transitions, and further investigation involving higher moments may provide deeper insights.

Future work could explore TNRC applications in higherdimensional tensor networks, neural network reservoirs, or other physical reservoirs. Applying TNRC to additional timeseries settings and examining why critical entanglement entropy seems to be a universal constant remain open questions. We plan to conduct further analyses on practical time-series



Fig. 3. (a) Test accuracy with respect to the normalized entanglement entropy for various bond dimensions. (b) The total IPC is plotted with respect to the normalized entanglement entropy  $\widetilde{S}$ 

data and develop theoretical boundaries.

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